Historical Inertia: A Neglected but Powerful Baseline for Long Sequence Time-series Forecasting

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ABSTRACT

Long sequence time-series forecasting (LSTF) has become increasingly popular for its wide range of applications. Though superior models have been proposed to enhance the prediction effectiveness and efficiency, it is reckless to neglect or underestimate one of the most natural and basic temporal properties of time series: history has inertia. In this paper, we introduce a new baseline for LSTF, named historical inertia (HI). In HI, the most recent historical data points in the input time series are adopted as the prediction results. We experimentally evaluate HI on 4 public real-world datasets and 2 LSTF tasks. The results demonstrate that up to 82% relative improvement over state-of-the-art works can be achieved. We further discuss why HI works and potential ways of benefiting from it.

CCS CONCEPTS

Applied computing → Forecasting.

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1 INTRODUCTION

Time series forecasting, i.e., given historical values of time series and making predictions for future time-slots, can be deemed as one of the main enablers of modern society. An accurate prediction model can benefit a wide range of applications, e.g., predicting stock prices [2, 11], monitoring traffic flows and electricity consumption [4, 7, 10, 13].

Rather than the typical setting of predicting values of a limited number of time-steps, i.e. 48 steps or fewer [4, 7, 10, 11], an emerging line of work focuses on the problem of long sequence time-series forecasting (LSTF), where up to 720 steps can be predicted at a time [13]. Such an increasing sequence length can be troublesome

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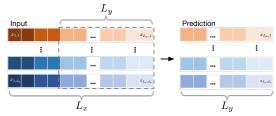


Figure 1: The proposed baseline HI, illustrated in the scenario of multivariate time series forecasting. HI directly takes the most recent time steps in the input as prediction. L_x is the input length and L_y is the prediction length. d_x denotes the number of variables in inputs.

to most existing works, which are designed for relatively short prediction horizons.

To deal with the challenges of effectively modeling temporal correlations in long sequence and efficiently operating on long inputs and outputs, the state-of-the-art (SOTA) work Informer [13] proposes a novel variant of Transformer [9] to reduce time and space complexity while maintaining prediction accuracy, which is indeed a breakthrough. Despite that the extensive experiments on five real-world datasets demonstrate Informer's superiority to its baselines, the enhanced performance can be limited when considering the baseline of taking the most recent values in inputs as outputs, which can be referred to as the historical inertia (HI).

In this paper, we first address this issue by providing an experimental evaluation of the proposed baseline HI and SOTA models and on a variety of public real-world datasets, and then make a comprehensive discussion on why HI is powerful and how we can benefit from HI.

2 PROBLEM AND THE PROPOSED BASELINE

Long Sequence Time-series Forecasting (LSTF): At time t, given a L_x -length time series, i.e., $X(t) = \{X_1(t), ..., X_{L_x}(t)\}$, where $X_i(t) = [x_{i,1}(t), ..., x_{i,d_x}(t)] \in \mathbb{R}^{d_x}, i \in [1, ..., L_x]$, is the observed univariate $(d_x = 1)$ or multivariate $(d_x > 1)$ variable at the i-th time-stamp, the goal of LSTF is to predict the corresponds L_y -length sequence Δ steps ahead, i.e., $\mathcal{Y}(t) = [Y_1(t), ..., Y_{L_y}(t)]$, where $Y_i(t) = [y_{i,1}(t), ..., y_{i,d_y}(t)] \in \mathbb{R}^{d_y}$ and $d_x \geq d_y \geq 1$. When $d_x = d_y$, $\mathcal{Y}(t) = [X_{L_x + \Delta + 1}(t), ..., X_{L_x + \Delta + L_y}(t)]$.

Historical Inertia: The historical inertia (HI) baseline takes L_y -length subsequence of $\mathcal{X}(t)$ as prediction results, i.e., $\hat{\mathcal{Y}}(t) = [X_{L_x-L_y+1}(t),..,X_{L_x}(t)]$.

Note that HI requires prediction length to be no longer than the input length, i.e., $L_x \ge L_y$, which is not necessary for learning-based LSTF models. Considering that in real application scenarios, the dataset is usually orders of magnitude larger than L_y , this

condition can be easily achieved. An illustration of the proposed baseline is shown in Figure 1.

3 EXPERIMENT AND RESULTS

3.1 Datasets and Metrics

We compare HI with SOTA models on four real-world public datasets. **ETT** (Electricity Transformer Temperature) ¹: The ETT dataset from the Informer paper contains 2 years of electric power deployment collected from two Chinese counties. There are 7 features in total. Three sub-datasets are included in our experiments, i.e. ETTh1 and ETTh2 with a 1-hour sampling frequency and ETThm1 with a 15-min sampling frequency. In the univariate forecasting task, the feature "oil temperature" is chosen as the prediction target.

Electricity ²: The raw dataset of Electricity is from the UCI Machine Learning Repository ³, which contains electricity consumption of 370 clients every 15 minutes from 2011 to 2014. We use the pre-processed dataset from [4], which reflects the hourly consumption of 321 clients from 2012 to 2014. The last client (column) is used as the prediction target in the univariate forecasting task.

Statistics of the above datasets can be found in Table 1.

Table 1: Statistics of dataset.

Dataset	# samples	# variables	Sample rate
ETTh1	17420	7	1 hour
ETTh2	17420	7	1 hour
ETTm1	69680	7	15 minutes
Electricity	26304	321	1 hour

As a common practice, we evaluate the models by two metrics: Mean Square Error (MSE) and Mean Absolute Error (MAE), which are computed as:

$$MSE = \frac{1}{T} \sum_{t=1}^{T} \frac{1}{L_y \times d_y} \sum_{i=t_1}^{t_{L_y}} \sum_{j=1}^{d_y} (\hat{y}_{i,j}(t) - y_{i,j}(t))^2, \tag{1}$$

$$MAE = \frac{1}{T} \sum_{t=1}^{T} \frac{1}{L_y \times d_y} \sum_{i=t}^{t_{L_y}} \sum_{i=1}^{d_y} |\hat{y}_{i,j}(t) - y_{i,j}(t)|$$
 (2)

where \hat{y} is the prediction output, y is the ground-truth value, $t \in [t_1, t_T]$ is the time instance in test set.

All above settings are consistent with the Informer paper. Note that we eliminate the dataset Weather that is also used in the paper since only raw data is available and the preprocessing operations are unclear.

3.2 Competitors

- 3.2.1 Univariate LSTF SOTA Models. Eight models ranging from traditional statistical methods to recent-proposed deep models are included as competitors for the task of univariate time series forecasting.
 - **Prophet** [8]: A regression model that models common feature of time series in scale-aware way.

- ARIMA [2]: An autoregressive integrated moving averagebased model for stock price prediction.
- **DeepAR** [6]: An autoregressive recurrent neural network.
- LSTMa [1]: A recurrent neural network-based neural machine translation model designed for long sentences.
- **Reformer** [3]: An efficient variant of Transformer using locality-sensitive hashing and reversible residual layers.
- LogTrans [5]: An efficient variant of Transformer using convolutional attention and sparse attention.
- Informer [13]: An efficient variant of Transformer using ProbSparse self-attention and self-attention distilling.
- Informer- [13]: A variant of Informer removing the Prob-Sparse self-attention mechanism.

3.2.2 Multivariate LSTF SOTA Models. Besides above mentioned LSTMa, Reformer, LogTrans, Informer and Informer-,

 LSTNet [4]: A deep neural network that combines convolutional neural networks and recurrent neural networks,

is used as a competitor in the task of multivariate time series forecasting.

3.3 Implementation Details

Basically, we follow the common practice in the community as described in [13]. Δ is fixed as 1. Prediction length is set as [24, 48, 168, 366, 720] for ETTh1 and ETTh2, [24, 48, 96, 288, 672] for ETTm1 and [48, 168, 366, 720, 960] for Electricity. We split the ETT datasets into 12:4:4 and Electricity dataset into 15:3:4 for training, validation, and test. The above implementation settings are consistent with the Informer paper. Since the method of HI doesn't require training, when the dataset split is fixed, the performance is fixed. Thus, only one iteration is sufficient to compute the final results.

3.4 Main Results

Table 2 and Table 3 provide the main experimental results of HI and SOTA models. The best results are highlighted in bold. The last line in each Table calculates HI's relative improvement over the best SOTA model, which is calculated as (best_SOTA_Model – HI)/best_SOTA_Model. Numbers in green indicate positive and in red indicate negative. All reported results are on the test set. Besides the results of HI, numbers are referenced from the updated results on the paper of Informer [13]. We also follow the same scaling strategy as Informer does.

We observe that HI achieves state-of-the-art results in many cases, especially for the task of multivariate forecasting, in which the relative improvement can be up to 82%. In the following, we discuss experimental results of univariate and multivariate LSTF respectively.

3.4.1 Univariate LSTF Results. Table 2 shows that in the task of predicting a single variable over time, HI outperforms SOTA models significantly on ETTh1 and ETTm1 datasets. Informer and its variant almost dominate the ETTh2 dataset while DeepAR, Informer, and HI claim part of the best results on the Electricity dataset. The relative improvement brought by HI can be up to 80% on MSE and 58% on MAE.

¹https://github.com/zhouhaoyi/

²https://github.com/laiguokun/multivariate-time-series-data

 $^{^3} https://archive.ics.uci.edu/ml/datasets/ElectricityLoadDiagrams 2011 2014$

ETTh1 ETTh2 ETTm1 Dataset Electricity Method 96 Metric 48 168 336 720 24 48 168 336 720 24 48 288 672 48 168 336 720 960 $|\ 0.115\ 0.168\ 1.224\ 1.549\ 2.735\ |\ 0.199\ 0.304$ 2.145 2.096 3.355 0.120 0.133 2.747 | 0.524 2.725 0.194 0.452 2.246 4.243 6.901 Prophet 0.275 0.330 0.763 1.820 3.253 0.381 0.462 1.068 2.543 4.664 0.290 0.305 0.396 0.574 1.174 0.595 1.273 3.077 1.415 4.264 $0.175\ \ 0.396\ \ 0.468\ \ 0.659\ \big|\ 3.554\ \ 3.190\ \ 2.800\ \ 2.753\ \ 2.878\ \big|\ 0.090\ \ 0.179$ 0.639 | 0.879 | 1.032 | 1.136 | 1.251 | 1.370 ARIMA 0.284 0.424 0.504 0.593 0.766 0.445 0.474 0.595 0.738 1.044 0.206 0.306 0.399 0.697 | 0.764 0.833 0.876 0.933 0.982 MSE $|0.107 \ 0.162 \ 0.239 \ 0.445 \ 0.658 \ |0.098 \ 0.163 \ 0.255 \ 0.604 \ 0.429 \ |0.091 \ 0.219$ 0.364 0.948 2.437 | **0.204 0.315 0.414** 0.563 0.657 DeepAR 0.280 0.327 0.422 0.552 0.707 0.263 0.341 0.414 0.607 0.580 0.243 0.362 0.496 0.795 1.352 **0.357** 0.436 0.519 0.595 0.683 MSE 0.114 0.193 0.236 0.590 0.683 0.155 0.190 0.385 0.558 0.640 0.121 0.305 0.287 0.524 1.064 | 0.493 | 0.723 | 1.212 | 1.511 | 1.545 LSTMa MAE 0.358 0.392 0.698 0.768 0.307 0.348 0.514 0.606 0.681 0.233 0.411 0.420 0.584 0.873 0.539 0.655 0.898 0.966 0.272 MSE 1.793 | 0.971 0.222 0.284 1.522 1.860 2.112 0.263 0.458 1.029 1.668 2.030 0.095 0.249 0.920 1.671 3.528 4.891 Reformer MAE 0.389 0.445 1.191 0.124 1.436 0.437 0.545 0.879 1.228 1.721 0.228 1.245 1.528 0.8841.587 2.196 4.047 MSF. 0.103 0.167 0.207 0.230 0.273 0.102 0.169 0.246 0.267 0.303 0.065 0.078 0.199 0.411 0.598 | 0.280 | 0.454 | 0.514 | 0.558 | 0.624 LogTrans MAE 0.259 0.328 0.375 0.398 0.463 0.255 0.348 0.422 0.437 0.493 0.702 0.429 0.529 0.202 0.220 0.386 0.572 0.563 0.609 0.645 MSE 0.092 0.161 0.187 0.215 0.257 0.099 0.159 0.235 0.258 0.285 0.034 0.066 0.187 0.519 | 0.238 | 0.442 | 0.501 | 0.543 | 0.594 0.409 Informer-MAE 0.246 0.322 0.355 0.369 0.421 0.241 0.317 0.390 0.423 0.442 0.160 0.194 0.384 0.548 0.665 | 0.368 | 0.514 | 0.552 | 0.578 | 0.638 MSE 0.098 0.158 0.183 0.222 0.269 | **0.093** 0.155 **0.232** 0.263 **0.277** | 0.030 0.069 0.239 0.447 0.194 0.401 0.512 0.489 0.540 0.582 Informer MAE 0.247 0.319 0.346 0.387 0.435 0.240 0.314 **0.389 0.417 0.431** 0.137 0.203 0.372 0.554 0.644 0.359 0.503 0.528 **0.571 0.608 | 0.046 0.069 0.116 0.137 0.186 |** 0.095 **0.150** 0.257 0.318 0.449 **| 0.023 0.039 0.046 0.081 0.115** | 0.872 0.328 0.415 1.178 1.302 HI **0.166 0.210 0.271 0.306 0.351 0.231 0.300** 0.409 0.465 0.549 0.115 0.156 0.167 0.229 0.270 0.690 0.393 0.463 0.836 0.894 MSE 28% 23% 23% 41% 80% 118% 124% Improve 33% 93% 10% MAE 34% 37% 17% 4% 5% 12% 27% 16% 20% 55% 58% 58% 11% 46% 47%

Table 2: Summary of univariate long sequence time-series forecasting comparison results.

3.4.2 Multivariate LSTF Results. Table 3 compares HI against SOTA models for the task of predicting multiple variables over time. We observe that almost all the best results are achieved by HI and the improvement is significant. In the task of predicting 168 and 720 steps ahead on the ETTh2 dataset, competitors' best MSE are 3.242 and 3.467, HI reduces them to 0.572 and 0.635, bringing in up to 82% relative improvement.

3.5 Study of HI

While Table 2 and Table 3 already demonstrate HI's performance against SOTAs, in this section, we emphasize the potential of HI serving as an effective trick by showing how it can help to improve the of a basic model. We combine HI with another simple method: multi-layer perceptron (MLP) to further explore the effect of HI. The implementation of MLP is the same for all tests in this section. We use a 2-layer MLP with embedding dimension 200. A 1d batch normalization layer, a ReLU layer, and a dropout layer with a dropout rate of 0.05 are added to each hidden layer of the MLP. We set the batch size as 32. The training epoch is set as 30 with early stopping patience 3 on validation loss, which is defined as MSE. The learning rate is initialized as 0.0003 and will be reduced by half every epoch. For each test, we run 5 iterations and report the mean values as the final results, as shown in Table 4 and Table 5. Informer is also included for comparison.

The very first observation is that MLP itself is also a strong baseline, which outperforms HI and state-of-the-art models across almost all datasets and prediction lengths. Regardless of this point, we take MLP as a basic model, and evaluate the ensemble of MLP and HI. We operate weighted summation over MLP's and HI's outputs to get the final prediction. The weights of the two models are set as 0.5/0.5. From Table 4 and Table 5, it could be concluded that this hybrid model can obtain better results in many cases, which is especially evidential for the task of univariate forecasting. MLP + HI brings up to 32% relative improvement over HI and 45%

relative improvement over MLP on MSE, and 20%, 27% relative improvement on MAE.

4 DISCUSSION

Given the above results, it could be concluded that though naive, HI is a strong baseline but unfortunately neglected for comparison in LSTF research. However, it is more important why it is powerful and how we could benefit from it.

4.1 Why Historical Inertia Works

A common belief is that predictable time series should have tractable patterns in phase and magnitude. We credit the very first reason HI is powerful to that it guarantees the outputs are in similar magnitude of the inputs. This is especially true in the scenario of long sequence time-series forecasting because the temporal patterns of a time series can be steadier if viewed in the long run.

However, the phase is much trickier. On the one hand, longer time series provide more evident periodic patterns that can not be reflected in short horizons. This increases the chance that the HI be of a similar phase as the prediction target, especially in the case that the prediction length is an exact integer multiple of the time series' period when there is any. On the other hand, HI could also badly hurt the prediction results when 1) there is no periodic pattern; 2) the periodic pattern is not included in historical data; 3) or the historical data is in the opposite phase as the prediction target. The multivariate prediction results on the ETTm1 dataset serve as good evidence of the above statements. Since the data was sampled by 15-minute, a prediction length of 24 or 48 is too short to reflect periodic patterns. Therefore, HI performs much worse than SOTA models. However, for predicting lengths of 96, 288, and 672, where the 1-day (4×24 data-points) period is well covered, the relative improvement surges.

Data	set	[ETTh1	l				ETTh2 ETTm1			El	Electricity								
Method	Metric	24	48	168	336	720	24	48	168	336	720	24	48	96	288	672	48	168	336	720	960
LSTMa															1.740 1.124						
Reformer															1.820 1.094						
LogTrans															1.462 1.320						
LSTNet															1.257 2.076						
Informer-															1.162 0.879						
Informer															1.056 0.786						
НІ							!					!			0.526 0.444						
Improve	MSE MAE	26% 29%	27% 32%	30% 32%	37% 39%	41% 37%	63% 54%	74% 63%	82% 68%	78% 61%	82% 64%	356% 95%	259% 75%	38% 37%	50% 44%	45% 45%	2% 16%	40% 34%	34% 28%	20% 0%	13% 14%

Table 3: Summary of multivariate long sequence time-series forecasting comparison results.

Table 4: Summary of univariate long sequence time-series forecasting comparison results with MLP.

Method		Infori	mer	HI		MLP		MLP -	+ HI
Dataset	Metric	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE
	24	0.098	0.247	0.046	0.166	0.046	0.165	0.037	0.146
	48	0.158	0.319	0.069	0.210	0.064	0.193	0.104	0.265
ETTh1	168	0.183	0.346	0.116	0.271	0.099	0.243	0.103	0.248
	336	0.222	0.387	0.137	0.306	0.170	0.335	0.093	0.243
	720	0.269	0.435	0.186	0.351	0.313	0.483	0.307	0.482
	24	0.093	0.240	0.095	0.231	0.078	0.214	0.074	0.207
	48	0.155	0.314	0.150	0.300	0.105	0.252	0.104	0.249
ETTh2	168	0.232	0.389	0.257	0.409	0.185	0.337	0.164	0.316
	336	0.263	0.417	0.318	0.465	0.216	0.371	0.194	0.351
	720	0.277	0.431	0.449	0.549	0.281	0.428	0.314	0.451
ETTm1	24	0.030	0.137	0.023	0.115	0.020	0.110	0.016	0.094
	48	0.069	0.203	0.039	0.156	0.029	0.128	0.030	0.132
	96	0.194	0.372	0.046	0.167	0.070	0.210	0.069	0.208
	288	0.401	0.554	0.081	0.229	0.091	0.238	0.107	0.264
	672	0.512	0.644	0.115	0.270	0.199	0.372	0.088	0.227
	48	0.239	0.359	0.872	0.690	0.266	0.370	0.251	0.354
	168	0.447	0.503	0.328	0.393	0.275	0.372	0.248	0.347
Electricity	336	0.489	0.528	0.415	0.463	0.331	0.414	0.300	0.382
,	720	0.540	0.571	1.178	0.836	0.390	0.454	0.363	0.453
	960	0.582	0.608	1.302	0.894	0.442	0.499	0.464	0.523

4.2 Benefit from Historical Inertia

Being of so much power, HI has the potential to serve as an effective trick. We now discuss possible ways of implementation from the perspectives of post-process and pre-process.

4.2.1 Hybrid Model. A model may benefit from combining the basic model's and HI's results in a post-process fashion. For example, the simplest implementation would be making a weighted summation of the two prediction sequences as the proposed MLP + HI does.

4.2.2 AutoML. The modeling capacity of complex architectures is definitely valuable, but just in some cases the answer to the question can be so simple that might not be answered well when it is complicated by the model. It is desirable that a model's structure or complexity can be adaptable to the input, which is also known as automated machine learning (AutoML) (e.g. Yao et al. 12). A simple

Table 5: Summary of multivariate long sequence time-series forecasting comparison results with MLP.

Method		Infor	ner	HΙ		MLP		MLP -	HI +
Dataset	Metric	MSE	MAE	MSE	MAE	MSE	MAE	MSE	MAE
	24	0.577	0.549	0.426	0.390	0.312	0.361	0.305	0.353
	48	0.685	0.625	0.498	0.423	0.353	0.386	0.346	0.377
ETTh1	168	0.931	0.752	0.653	0.509	0.450	0.451	0.453	0.444
	336	1.128	0.873	0.690	0.527	0.489	0.484	0.526	0.497
	720	1.215	0.896	0.714	0.563	0.533	0.526	0.581	0.552
	24	0.720	0.665	0.266	0.304	0.186	0.279	0.184	0.277
ETTh2	48	1.457	1.001	0.379	0.374	0.247	0.319	0.253	0.321
	168	3.489	1.515	0.572	0.481	0.370	0.411	0.378	0.406
	336	2.723	1.340	0.567	0.500	0.410	0.443	0.471	0.479
	720	3.467	1.473	0.635	0.530	0.797	0.648	0.698	0.595
	24	0.323	0.369	1.395	0.720	0.227	0.298	0.225	0.298
ETTm1	48	0.494	0.503	1.668	0.821	0.298	0.345	0.300	0.350
	96	0.678	0.614	0.423	0.387	0.335	0.372	0.331	0.369
	288	1.056	0.786	0.526	0.444	0.360	0.391	0.361	0.389
	672	1.192	0.926	0.655	0.508	0.438	0.437	0.447	0.444
	48	0.344	0.393	0.328	0.329	0.183	0.272	0.178	0.265
	168	0.368	0.424	0.212	0.279	0.173	0.275	0.162	0.258
Electricity	336	0.381	0.431	0.247	0.312	0.186	0.291	0.176	0.277
,	720	0.406	0.443	0.469	0.439	0.219	0.321	0.223	0.322
	960	0.460	0.548	0.518	0.471	0.235	0.335	0.243	0.339

implementation could be when a specific dataset is given, the model may first analyze its temporal patterns in a pre-processed way, and then score whether the basic model, HI, or some median variants should be used for prediction.

5 CONCLUSION

In this paper, we propose a baseline for LSTF, named HI. It directly takes the most recent time steps in the input as output. Extensive experiments in four public real-world datasets validate the strength of HI across different prediction lengths. We hope HI could serve as a basement and spark future LSTF research.

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